

Course: Numerical Methods For Engineers

Branch: Civil, Mechanical

UNIT- III



SOLUTIONS OF EQUATIONS AND EIGHEN VALUE PROBLEMS

IMPORTANT FORMULAE

NEWTON RAPHSON METHOD

$$\phi(x_n) = x_{n+1} = x_n - \frac{\int (x_n)}{\int (x_n)}$$
, $n = 0, 1, 2, ..., |\phi'(x)| < 1$

UNIT- V

NUMERICAL SOLUTION OF ORDINARY DIFFERENTIAL EQUATIONS

TAYLOR'S SERIES

$$y_{n+1} = y_n + \frac{h}{1!} y_n' + \frac{h^2}{2!} y_n'' + \frac{h^3}{3!} y_n''' + \cdots$$

EULER'S METHOD

$$y_{n+1} = y_n + h + (x_n, y_n)$$

MCDIFIED EULER'S METHOD

RUNGE-KUTTA METHODS OF FOURTH ORDER

$$K_{1} = h \cdot k (x_{1}, y_{1})$$

$$K_{2} = h \cdot k \left(x + \frac{h}{2}, y_{1} + \frac{k_{1}}{2}\right)$$

$$K_{3} = h \cdot k \left(x_{1} + \frac{h}{2}, y_{1} + \frac{k_{2}}{2}\right)$$

$$K_{4} = h \cdot k \left(x_{1} + h, y_{1} + k_{3}\right)$$

$$\Delta y = \frac{1}{h} \left(k_{1} + 2k_{2} + 2k_{3} + k_{4}\right)$$



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PREDICTOR - CORRECTOR METHODS

PREDICTOR FORMULA:

CORRECTOR FORMULA

BOUNDARY VALUE PROBLEMS

$$y_i'' = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$



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UNIT- IN IMPORTANT FORMULAS.

O. Lagrange Interpolation formula.

$$y = f(x) = \frac{(x - y_1)(x - y_2)(x - y_3)}{(y_0 - y_1)(x_0 - y_2)(y_0 - y_3)} y_0 + \frac{(x - y_0)(x - y_2)(x - y_3)}{(x_1 - y_0)(x_1 - y_2)(x_1 - y_3)} y_1 + \frac{(x - y_0)(x_1 - y_2)(x_1 - y_3)}{(y_1 - y_0)(x_2 - y_1)(x_2 - y_3)} y_2 + \frac{(x - y_0)(x_1 - y_1)(x_2 - y_2)}{(y_3 - y_0)(x_3 - y_1)(x_3 - y_2)} y_3.$$

2). Newton's divided différence interpolations

3. Newton's forward Interpolation formula for equal intervals.

$$y(n) = y_0 + \frac{u}{16} \Delta y_0 + \frac{u(u-1)}{26} \Delta^2 y_0 + \frac{u(u-1)(u-2)}{36} \Delta^3 y_0^2 + \frac{u(u-$$

@ Newton's Backword interpolation formula.

$$y(x) = y_n + \frac{y}{1!} \nabla y_n + \frac{y(y+1)}{2!} \nabla^2 y_n + \frac{y(y+1)(y+2)}{3!} \nabla^3 y_n^4 \dots$$
Here $y = \frac{x - x_0}{h_0}$.

(5). Newton's forward difference formula.

$$\left(\frac{dy}{dx}\right)_{x=x_0} = \frac{1}{h} \left[\Delta y_0 - \frac{1}{2}\Delta^2 y_0 + \frac{1}{3}\Delta^3 y_0 - \frac{1}{4}\Delta^4 y_0 + \dots\right]$$

$$\left(\frac{d^2y}{dx^2}\right)_{x=y_0} = \frac{1}{h^2} \left[\Delta^2 y_0 - \Delta^3 y_0 + \frac{11}{12} \Delta^4 y_0 + \cdots \right]$$

$$\left(\frac{d^3y}{dx^3}\right)_{x=X_0} = \frac{1}{h^3} \left[\Delta^3 y_0 - \frac{3}{2} \Delta^4 y_0 + \cdots \right]$$

1. Newton's Backward difference formula.

$$\left(\frac{dy}{dx}\right)_{x=x_n} = \frac{1}{h} \left[\nabla y_n + \frac{1}{2} \nabla^2 y_n + \frac{1}{3} \nabla^3 y_n + \cdots \right]$$

$$\left(\frac{d^{2}y}{dx^{2}}\right)_{x=y_{n}} = \frac{1}{h^{2}} \left[\nabla^{2}y_{n} + \nabla^{3}y_{n} + \frac{11}{12} \nabla^{4}y_{n} + \cdots \right]$$

$$\left(\frac{d^3y}{dx^3}\right)_{x=x_n} = \frac{1}{h^3} \left[\nabla^3 y_n + \frac{3}{2} \nabla^4 y_n + \cdots \right]$$

O. Trapezoidal rule.

$$\hat{I} = \frac{h}{2} \left[(y_0 + y_n) + \lambda (y_1 + y_2 + \dots + y_{n-1}) \right]$$

(8). Simpronis 1/3 rule,

$$T = \frac{b}{3} \left[(y_0 + y_0) + 2(y_1 + y_3 + y_5 + \dots) + 4(y_2 + y_4 + \dots) \right]$$

9. Simpson's 3/2 rule.

$$\underline{T} = \frac{3h}{8} \left[(y_0 + y_0) + 3 (y_1 + y_2 + y_4 + \dots + y_{n-1}) + 2 (y_3 + y_6 + \dots -) \right].$$